DATA SHEET

T 8394 EN

Type 3725 Electropneumatic Positioner



CE Ex certified

Application

Single-acting positioner for attachment to pneumatic globe and rotary valves. Self-calibrating, automatic adaptation to valve and actuator.

| Reference variable | 4 to 20 mA |
|--------------------|---------------------|
| Travel | 5 to 50 mm |
| Opening angle | 24 to 100° |

The positioner ensures a predetermined assignment of the valve position (controlled variable x) to the input signal (reference variable w). It compares the input signal received from a control system to the travel or rotational angle of the valve and issues a corresponding output signal pressure (output variable y).

Special features

- Simple direct attachment to SAMSON Type 3277 Actuator (120 to 700 cm², see Fig. 1)
- Attachment according to IEC 60534-6-1 (NAMUR)
- Attachment to rotary actuators according to VDI/ VDE 3845 (see Fig. 3)
- Attachment to Type 3372 Actuator for Series V2001 Valves (see Fig. 2)
- Easy operation with intuitive navigation menu using three capacitive keys
- LCD easy to read in any mounting position thanks to selectable reading direction
- Variable, automatic start-up
- Preset parameters (only values deviating from the standard need to be adjusted)
- All parameters saved in non-volatile EEPROM
- Tight-closing function can be activated
- Continuous zero monitoring
- Non-contact position sensing
- Unaffected by environmental effects and steam hammering

Version

- Electropneumatic positioner with on-site operation and LCD
 - Type 3725-000, without explosion protection
 - Type 3725-110, explosion protection acc. to ATEX, STCC
 - Type 3725-113, explosion protection acc. to GOST
 - Type 3725-130, explosion protection acc. to CSA



Principle of operation

The Type 3725 Electropneumatic Positioner is mounted on pneumatic control valves and used to assign the valve position (controlled variable x) to the control signal (reference variable w). The positioner compares the electric control signal of a control system to the travel or opening angle of the control valve and issues a signal pressure (output variable y) for the pneumatic actuator.

The positioner mainly consists of the following components (see Fig. 4):

- Magnetoresistive sensor (2)
- Analog i/p converter (6) with a downstream air booster (7)
- Electronics unit with microcontroller (4)

The travel or opening angle is measured by the pick-up lever, non-contact magnetoresistive sensor and downstream electronics.

The pick-up lever is connected to a magnet inside the device. The motion of the pick-up lever causes the direction of the magnetic field to change. This change is sensed by the sensor (2). The electronics unit determines the current position of the actuator stem or opening angle from this information. The position of the actuator stem or opening angle is transmitted to the microcontroller (3) over the A/D converter (4). The PD control algorithm in the microprocessor (4) compares this actual position to the 4 to 20 mA control signal after it has been converted by the A/D converter. In case of a system deviation, the activation of the i/p module (6) is changed so that the actuator of the valve (1) is pressurized or vented accordingly over the downstream booster (7). The supply air is supplied to the booster and the pressure regulator (8).

Operation

A user-friendly, intuitive concept using three capacitive keys and an LCD has been developed: users select parameters by touching the arrow keys and confirm the settings with the confirmation key. In the menu, all parameters are listed in one level, meaning there is no need to search through submenus. All parameter settings can be read and changed on site.

The menu is structured with all parameters listed one after the other on the same level. This allows users to read and change parameters at the device.

All values are displayed on the LCD. The reading direction of the LCD can be rotated by $180^\circ.$

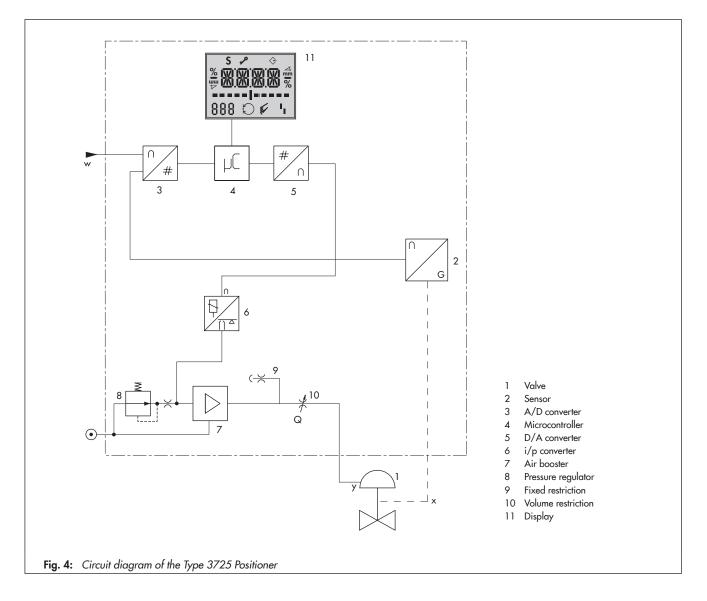


Table 1: Technical data

| Type 3725 Positioner | | | | | |
|--|---|--|--|--|--|
| Travel (adjustable) | Direct attachment to Type 3277:5 to 30 mmDirect attachment to Type 2780-2:6/12/15 mmAttachment to Type 3372 Actuator:15/30 mmAttachment according to IEC 60534-6 (NAMUR):5 to 50 mmAttachment to rotary actuators:24 to 100° | | | | |
| Reference variable w (reverse po- larity protection) | Signal range 4 to 20 mA · 2-wire unit Split-range operation 4 to 11.9 mA and 12.1 to 20 mA | | | | |
| Static destruction limit | ±33 V | | | | |
| Minimum current | 3.8 mA | | | | |
| Load impedance | Max. 6.3 V (corresponding to 315 Ω at 20 mA) | | | | |
| Supply air Air quality acc. to ISO 8573-1 | Supply air: 1.4 to 7 bar (20 to 105 psi) Max. particle size and density: Class 4 · Oil content: Class 3 · Pressure dew point: Class 3 or at least 10 K below the lowest ambient temperature to be expected | | | | |
| Signal pressure (output) | 0 bar up to the supply pressure \cdot Can be limited to approx. 2.3 bar by software | | | | |
| Characteristic | 3 characteristics for globe valves · 9 characteristics for rotary valves | | | | |
| Hysteresis | ≤0.3 % | | | | |
| Sensitivity | ≤0.1 % | | | | |
| Transit time | Only for actuators with initialization time > 0.5 s ¹⁾ | | | | |
| Direction of action | w/x reversible | | | | |
| Air consumption | ≤100 l _n /h with a supply pressure up to 6 bar and a signal pressure of 0.6 bar | | | | |
| Air output capacity Actuator (supply) Actuator (exhaust) | At Δp 6 bar: $8.5 \text{ m}_n^3/\text{h}$ At Δp = 1.4 bar : $3.0 \text{ m}_n^3/\text{h}$, $K_{Vmax}(20 \text{ °C}) = 0.09$ At Δp 6 bar: $14.0 \text{ m}_n^3/\text{h}$ At Δp = 1.4 bar : $4.5 \text{ m}_n^3/\text{h}$, $K_{Vmax}(20 \text{ °C}) = 0.15$ | | | | |
| Permissible ambient temperature | -20 to +80 °C -25 to +80 °C with metal cable gland The limits in the test certificates additionally apply for explosion-protected versions | | | | |
| Safety | | | | | |
| Influences | Temperature: ≤0.15 %/10 K Effect of vibration: ≤0.25 % up to 2000 Hz and 4 g according to IEC 770 Supply air: None | | | | |
| Electromagnetic compatibility | Complying with EN 61000-6-2, EN 61000-6-3 and NAMUR Recommendation NE 21 | | | | |
| Explosion protection ²⁾ | Intrinsic safety: ATEX, STCC, CSA, GOST | | | | |
| Degree of protection | IP66 | | | | |
| Conformity | CEE | | | | |
| Materials | | | | | |
| Housing | Polyphthalamide (PPA) | | | | |
| Cover | Polycarbonate (PC) ³ | | | | |
| External parts | Stainless steel 1.4571 and 1.4301 | | | | |
| Cable gland | M20x1.5, black polyamide (PA) | | | | |
| Vent plug | High-density polyethylene (PE-HD) | | | | |
| Weight | Approx. 0.5 kg | | | | |

For faster actuators, a volume restriction must be used. Otherwise, the initialization cannot be performed successfully.
See Table 2on page 4 for details on explosion protection certificates.
Makrolon[®]

Article code

| Positioner | | Туре 3725- | x | х | x | 0 | 0 | 0 | 0 | x | 0 | 0 |
|------------------|--|------------|---|---|---|---|---|---|---|---|---|---|
| With LCD and a | | | | Τ | | | | | | | | |
| Explosion prote | ction ¹⁾ | | | | | | | | | | | |
| Without | | | 0 | 0 | 0 | | | | | | | |
| ATEX | II 2 G Ex ia IIC T4 Gb | | 1 | 1 | 0 | | | | | | | |
| CCC Ex | Ex ia II T4 Gb | | 1 | 1 | 2 | | | | | | | |
| EAC | 1Ex ia IIC T4 Gb X | | 1 | 1 | 3 | | | | | | | |
| TR CMU 1055 | ll 2 G Ex ia IIC T4 Gb | | 1 | 1 | 6 | | | | | | | |
| CSA c/us | Ex ia IIC T4; Class I, Zone 0, AEx ia IIC T4; Class I, Div. 1, Groups A, B, C & D | | 1 | 3 | 0 | | | | | | | |
| Approval certifi | cates for ships | | | | | | | | | | | |
| Without | | | | | | | | | | 0 | | |
| Bureau Veritas (| Certification | | | | | | | | | 1 | | |

¹⁾ See Table 2 for details on explosion protection certificates.

| Table 2: | Summary c | of explosion | protection | certificates |
|----------|-----------|--------------|------------|--------------|
|----------|-----------|--------------|------------|--------------|

| Туре | Certification | | | Type of protection |
|-----------|---------------|-------------------------------|---|--|
| 3725-1000 | ATEX | Number Date | PTB 11 ATEX 2020 X 2019-02-25 | II 2 G Ex ia IIC T4 Gb |
| 3725-112 | CCC Ex | Number Date Valid until | 2021322307003871 2021-04-05 2026-04-04 | Ex ia II T4 Gb |
| 3725-113 | EAC | Number Date Valid until | RU C-DE. HA65.B.00510/20 2020-03-18 2025-03-18 | 1Ex ia IIC T4 Gb X |
| 3725-116 | TR CMU 1055 | Number Date Valid until | ZETC/35/2021 2021-07-26 2024-07-25 | II 2 G Ex ia IIC T4 Gb |
| 3725-130 | CSA c/us | Number Date | 2703735 X 2014-06-03 | Ex ia IIC T4; Class I, Zone O, AEx ia IIC T4; Class I, Div. 1, Groups A, B, C, D |

Table 3: Approval certificates for ships

| BV Time Annual Contificante | Number Date | 46564/B0 BV.pdf 2022-01-11 |
|------------------------------|----------------|-------------------------------|
| BV Type Approval Certificate | Valid until | 2022-01-11 2027-01-11 |

Mounting the positioner

The Type 3725 Electropneumatic Positioner can be attached directly to the Type 3277 Actuator over a connection block.

When attached to the Type 3277-5 Actuator (120 cm²), the signal pressure is routed over an internal bore in the actuator yoke to the actuator.

In actuators with fail-safe action "Actuator stem retracts" and in actuators with effective diaphragm areas of 240 cm² or larger, the signal pressure is routed to the actuator over readymade external piping.

Ordering text

Type 3725 Positioner Attachment Direct attachment to Type 3277 (without pneumatic connecting rail) Direct attachment to Type 3277 Actuator (120 to 700 cm²) Attachment according to IEC 60534-6-1 (NAMUR) Attachment to rotary actuators according to VDI/ VDE 3845 Attachment to Type 3278 Rotary Actuator (160/320 cm²) Pneumatic connecting rail G 1/4 or 1/4 NPT Pressure gauge (max. 6 bar) With/without

